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## Lab 5. Overload of the binary operators

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Class `my_vector` presents a vector in 3D.

```
class my_vector
{
private:
    double* cr; //cr[0] - x; cr[1] - y; cr[2] - z
public:
    my_vector() : cr(NULL) {}
    my_vector(double xx, double yy, double zz);
    my_vector(const my_vector& ob);
    ~my_vector() {
        if (cr)
            delete[] cr;
        cr = NULL;
    }
    my_vector& operator = (const my_vector & pb);

    my_vector operator + (const my_vector& right) const;
    my_vector operator * (const my_vector& right) const; //vector product: res = v1 x v2
    double operator * (const my_vector* right) const; //dot product: dot = v1 * v2

    friend istream& operator >> (istream& strm, my_vector& v);
    friend ostream& operator << (ostream& strm, const my_vector& v);

    void disp(const char* str);
private:
    void alloc(); //allocation of memory
};
```

For given class you must write the implementation of all operators and methods so that the `main` function below works correctly. Method `alloc` is used for dynamic memory allocation.

```
void my_vector::alloc()
```

```

{
    try
    {
        cr = new double[3];
        memset(cr, 0, 3 * sizeof(double));
    }
    catch (std::bad_alloc)
    {
        cout << "memory allocation error" << endl;
        system("pause");
        exit(1);
    }
}

```

The method `disp(...)` requires overloading of operator `<<` to output vector to the stream `cout`.

```

void my_vector::disp(const char *str)
{
    if (cr)
    {
        cout << str << ":" << *this << endl;
    }
}

int main()
{
    my_vector v1(1, 2, -1), v2(2, 1, 1), res;

    v1.disp("v1");
    v2.disp("v2");

    res = v1 + v2;
    res.disp("v1 + v2");

    my_vector res1 = v1 * v2;
    res1.disp("v1 x v2");
}

```

```
res1 = v2 * v1;
res1.disp("v2 x v1");

cout << "v1 * v2: " << v1 * (&v2) << endl;

my_vector v3(0, 0, 0);
cin >> v3;
v3.disp("v3");

return 0;
}
```